

NSF CyberTraining Winter Workshop

Introduction to Proper Orthogonal Decomposition

concepts, formulation and applications

Part III: POD - Examples & Method of Snapshots

Ming-Cheng Cheng

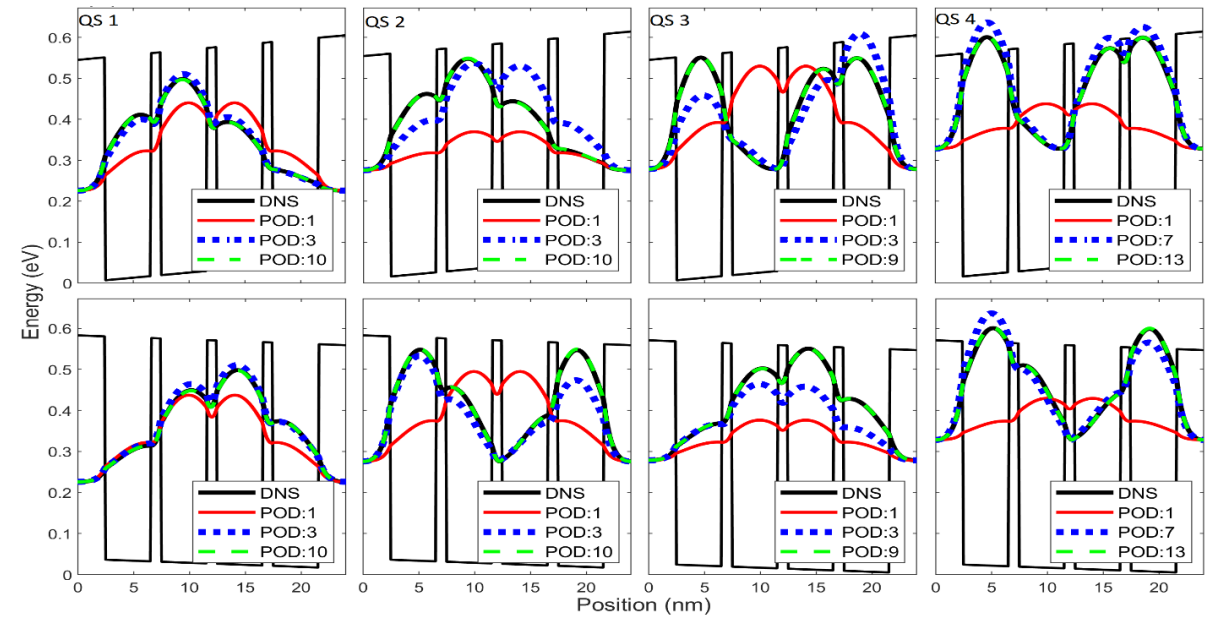
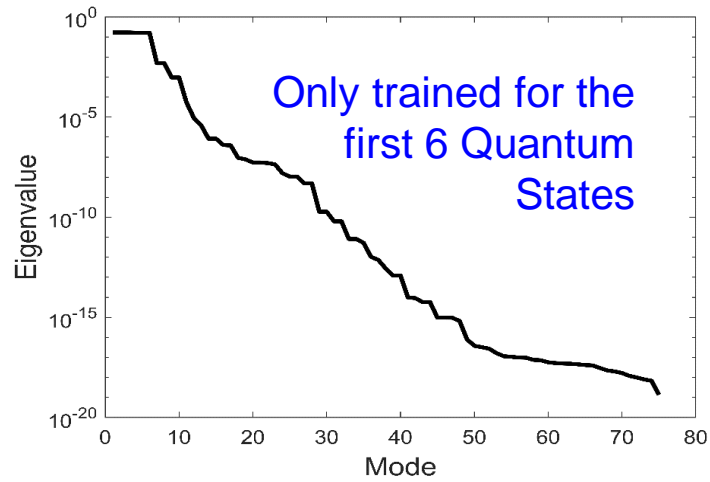
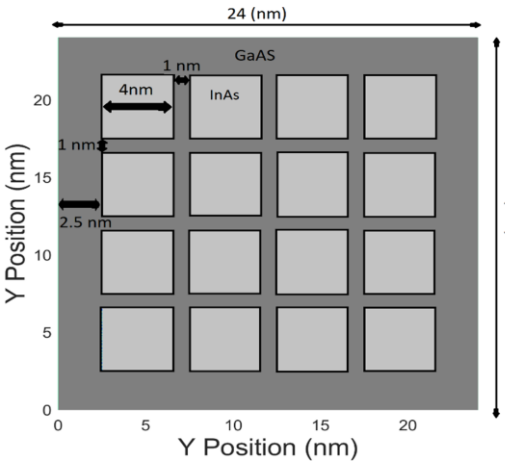
Department of Electrical & Computer Engineering
Clarkson University, Potsdam, NY 13699



National Science Foundation
WHERE DISCOVERIES BEGIN

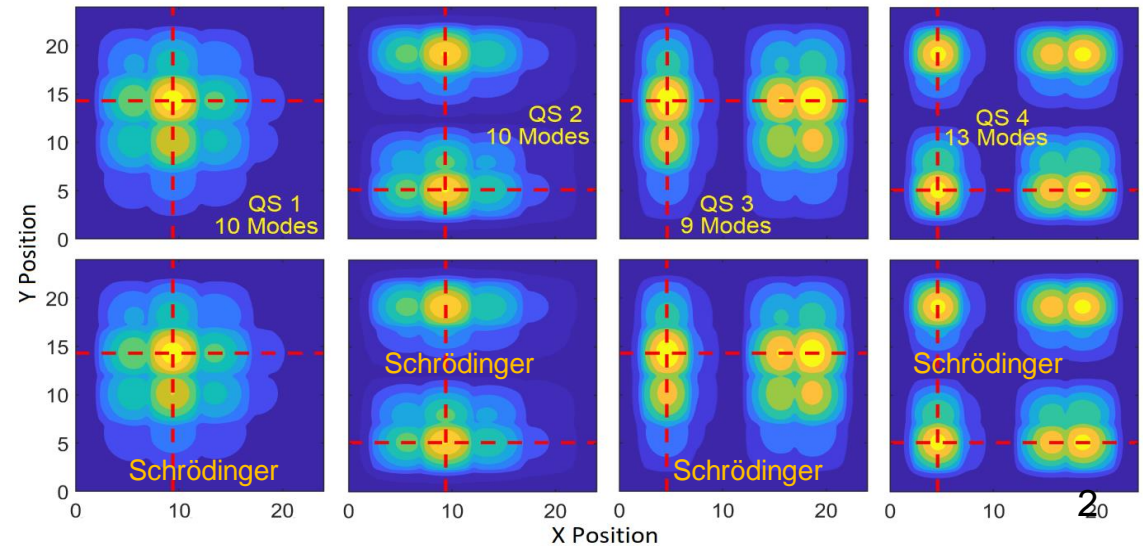
Supported by NSF OAC-2118079

2D Quantum Dot Structures



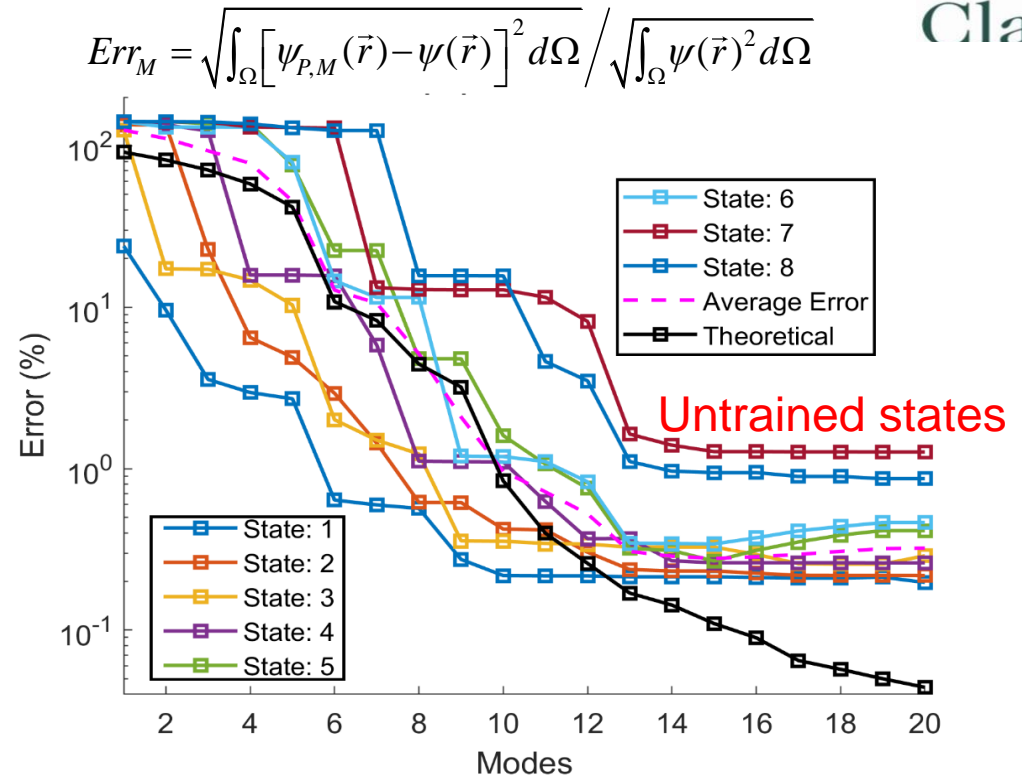
One-mode POD model predicts the average of the collected data

- **Training:** Apply electric fields in x and y directions **separately** to collect N_S sets of WF data
- **Simulation:** Demonstrated at electric field in a arbitrary direction



2D Quantum Dot Structures

Quantum State	POD Energy (eV)	DNS Energy (eV)	Difference (%)
1	0.226511	0.22602	0.21716
2	0.276652	0.275789	0.312542
3	0.27938	0.278522	0.30753
4	0.32952	0.32831	0.36803
5	0.357149	0.355488	0.466291
6	0.359669	0.358011	0.461969
7	0.409963	0.407977	0.48561
8	0.410194	0.40821	0.4847



Theoretical LS error

$$Err_{LS} = \sqrt{\frac{\sum_{i=M+1}^{N_s} \lambda_i}{\sum_{i=1}^{N_s} \lambda_i}}$$

Average LS errors over all QSs

$$Err_{M,ls,av} = \sqrt{\frac{\sum_{i=1}^{N_{QS}} \int_{\Omega} [\psi_{M,P,n} - \psi_n]^2 d\Omega}{N_{QS}}}$$

For a 2D quantum-dot structure, if 10 modes are used, a computational speedup near 130 times can be achieved.

States 7 & 8 were NOT trained

The computation was performed in Matlab on an i7 laptop PC.

Approach		6 Modes	8 Modes	10 Modes	12 Modes	14 Modes
POD time (s)	Eigenvalue solver	0.0000543	0.0000586	0.0000609	0.0000729	0.0000748
	Post Processing	0.0102472	0.0139769	0.0166791	0.0188029	0.0233854
DNS Eigenvalue Solver time (s)		2.1544969				



$$\int_{\Omega'} \langle Q(\vec{r}, t) \otimes Q(\vec{r}', t) \rangle \eta(\vec{r}') d\Omega' = \lambda \eta(\vec{r}), \quad (1)$$

$$\langle Q(\vec{r}, t) \otimes Q(\vec{r}', t) \rangle = \frac{1}{N_s} \sum_{j=1}^{N_s} Q(\vec{r}, t_j) Q(\vec{r}', t_j). \quad (2)$$

The $N_r \times N_r$ eigenvalue problem for a large-scale multi-dimensional structure may be enormously large and numerically prohibitive.

The Method of Snapshots: transform the eigenvalue problem from a $N_r \times N_r$ space domain to an $N_s \times N_s$ sampling domain. $N_r \gg N_s$

- For a 3D problem, N_r may be on the order of several 100,000's.
- For a dynamic problem, N_s is on the order of several 100's – several 1,000's; for steady problems, 10 -1,000

- Start with the discrete eigenvalue problem. Insert Eq. (2) into (1)

$$\frac{1}{N_s} \sum_{j=1}^{N_s} Q(\vec{r}, t_j) \int_{\Omega'} Q(\vec{r}', t_j) \eta(\vec{r}') d\Omega' = \lambda \eta(\vec{r}),$$



Solution of Eigenvalues and Eigenfunctions of 2-point Correlation Data

$$\frac{1}{N_t} \sum_{j=1}^{N_s} Q(\vec{r}, t_j) \int_{\Omega'} Q(\vec{r}', t_j) \eta(\vec{r}') d\Omega' = \lambda \eta(\vec{r}),$$

- Define the projection of the j th sampled data set onto the POD space as

$$u(t_j) = \int_{\Omega'} Q(\vec{r}', t_j) \eta(\vec{r}') d\Omega',$$

The eigenvalue problem becomes

$$\frac{1}{N_s} \sum_{j=1}^{N_s} Q(\vec{r}, t_j) u(t_j) = \lambda \eta(\vec{r})$$

- Multiply both sides of by $Q(\vec{r}, t_i)$ and perform an integral on each side,

$$\frac{1}{N_s} \sum_{j=1}^{N_s} \left[\int_{\Omega} Q(\vec{r}, t_i) Q(\vec{r}, t_j) d\Omega \right] u(t_j) = \lambda \int_{\Omega} Q(\vec{r}, t_i) \eta(\vec{r}) d\Omega$$

Define $A_{ij} = \frac{1}{N_s} \int_{\Omega} Q(\vec{r}, t_i) Q(\vec{r}, t_j) d\Omega$ (2 point correlation in time) $\rightarrow \mathbf{A}\vec{u} = \lambda\vec{u}$



- **Eigenvalue Problem in the sampling domain**

$$\mathbf{A}\vec{u} = \lambda\vec{u}; \quad \text{or} \quad \begin{bmatrix} A_{11} & \cdots & A_{1j} & \cdots & A_{1N_S} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ A_{i1} & \cdots & A_{ij} & \cdots & A_{iN_S} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ A_{N_t1} & \cdots & A_{N_tj} & \cdots & A_{N_tN_S} \end{bmatrix} \begin{bmatrix} u(t_1) \\ \vdots \\ u(t_j) \\ \vdots \\ u(t_{N_S}) \end{bmatrix} = \lambda \begin{bmatrix} u(t_1) \\ \vdots \\ u(t_j) \\ \vdots \\ u(t_{N_S}) \end{bmatrix}$$

Once the eigenvectors, $[\vec{u}_1, \vec{u}_2, \vec{u}_3, \dots, \vec{u}_{N_S}]$ are determined, each POD mode is obtained from a linear combination of numerical observations,

$$\eta_i(\vec{r}) = \frac{1}{\lambda N_S} \sum_{j=1}^{N_S} Q(\vec{r}, t_j) u_i(t_j)$$

The first N_S POD eigenvalues are identical to those derived from the N_S snapshots.



Concept Demonstration

Generation of Eigenvalues and POD modes

Use a dynamic function of $f(x,t)$ to train the POD modes. The function is described by 4 distinct characteristics,

$$f(x, t_i) = \sum_{j=1}^4 f_j(x, t_i),$$

- Space: $x = [x_1, x_2, \dots, x_k, \dots, x_{N_x-1}, x_{N_x}]^T = [0, 2, 4, \dots, 198]^T$ with $N_x = 100$ and grid size $\Delta x = 2$
- Time: $\Delta t = 0.2$ with the number of samples $N_s = 20$
- $f(x, t)$ includes a **Gaussian** function, **2 sinusoidal** functions with different frequencies in space and one **polynomial**. All these functions evolve in time described by different dynamic evolution rates either increasing or decreasing in time.

```
Nx = 100;  
Ns = 20;  
dx = 2;  
xx = linspace(0,Nx*dx-dx,Nx)';  
tt = 0.2*linspace(0,Ns-1,Ns)';
```



- $f_1(x, t) = f_{gaussian} = 500e^{-\left(\frac{x-100}{30}\right)^2}e^{-t}$
- $f_2(x, t) = f_{cos} = 200 \left[\cos\left(\frac{2\pi x}{x_{max}-20\Delta x}\right) + 1 \right] \left[1 - e^{-\frac{t^2}{2}} \right]$
- $f_3(x, t) = f_{sin} = 200 \left[\sin\left(\frac{6\pi x}{x_{max}-20\Delta x}\right) + 1 \right] e^{-\frac{t^2}{5}}$
- $f_4(x, t) = f_{poly} = (0.3x^2 - 100x + 200) [1 - e^{-t}]$

% 4 distinct functions

```
fgau = 500*exp(-((xx(1:Nx)-100)/30).^2); % decreasing in time
fcos= 200*(cos(2*pi/(xx(Nx)-20*dx)*xx(:))+1); % increasing in time, starting from 0
fsin= 200*(sin(6*pi/(xx(Nx)-20*dx)*xx(:))+1);% decreasing in time
fpoly = 0.3*xx(:).^2 - 100*xx(:) + 200; % increasing in time, starting from 0
```

%% Total function with dynamic evolution

```
ff_t = zeros(Nx,Ns);
for i=1:Ns
    ff_t(:,i) = fgau(:).*exp(-tt(i)) + fcos(:).*(1-exp(-tt(i)^2/2)) + ...
    fsin(:).*exp(-tt(i)^2/5) + fpoly(:).*(1-exp(-tt(i)));
end
```



Construct the 2-point correlation ($N_x \times N_x$) matrix for $f(x,t)$

- Average of the 2-point (autocorrelation) correlation matrix for $f(x,t)$: $\mathbf{F} = \frac{1}{N_s} \sum_{j=1}^{N_s} f(x, t_j) \otimes f(x', t_j)$ (average over N_s samples in time)

$$f(x, t_j) \otimes f(x', t_j) = \begin{bmatrix} f(x_1, t_j) \\ f(x_2, t_j) \\ \vdots \\ f(x_{N_x}, t_j) \end{bmatrix} \cdot \begin{bmatrix} f(x_1, t_j) \\ f(x_2, t_j) \\ \vdots \\ f(x_{N_x}, t_j) \end{bmatrix}^T$$

% Average of the 2-point spatial correlation matrix over time

FF = zeros(Nx,Nx);

for i = 1:Ns

FF = FF + ff_t(:,i)*ff_t(:,i)';

end

FF = FF/Ns;

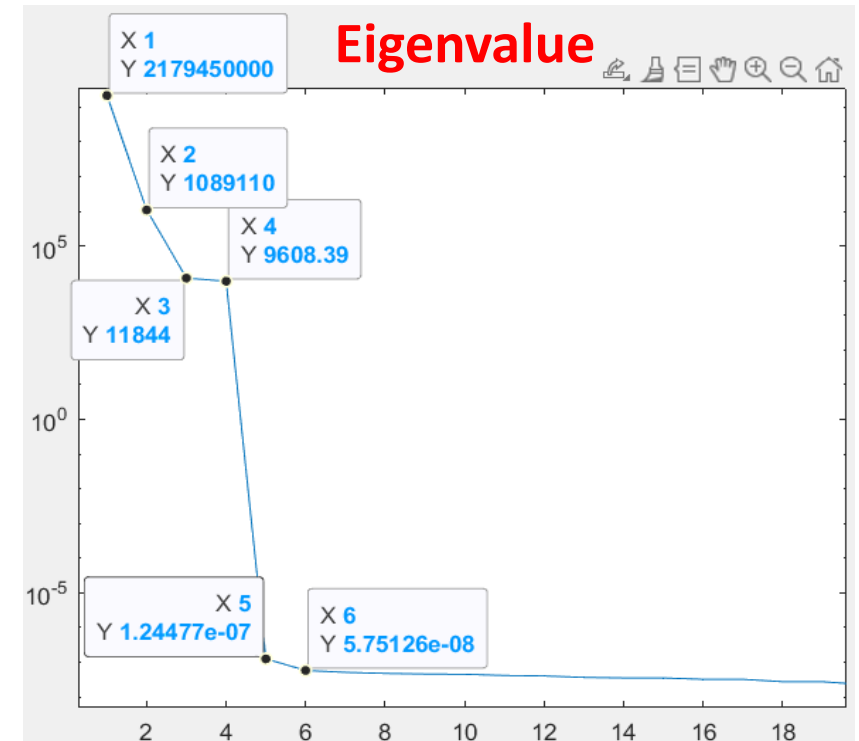


Solve the eigenvalues λ_i and the eigenfunctions (POD modes) η_i from f

The integral is not needed because of an equal spatial division is used
Arrange the eigenvalues in descending order and the POD modes with the same order

```
[V,DD] = eig(FF);
EigenV = flip(diag(DD));
V1 = flip(V,2);
semilogy(EigenV)
```

- The eigenvalue drops from the first mode to the 4th mode by 5 orders of magnitude and **becomes nearly zero beyond 4th mode. Why?**
- Note that $\frac{\lambda_1}{\lambda_5} \approx 10^{16}$ and λ becomes nearly flat because of the computer precision
- The decomposition effectively captures 4 distinct characteristics from the data with just 4 modes.
- That is, 4 modes are good enough to represent this dynamic problem.

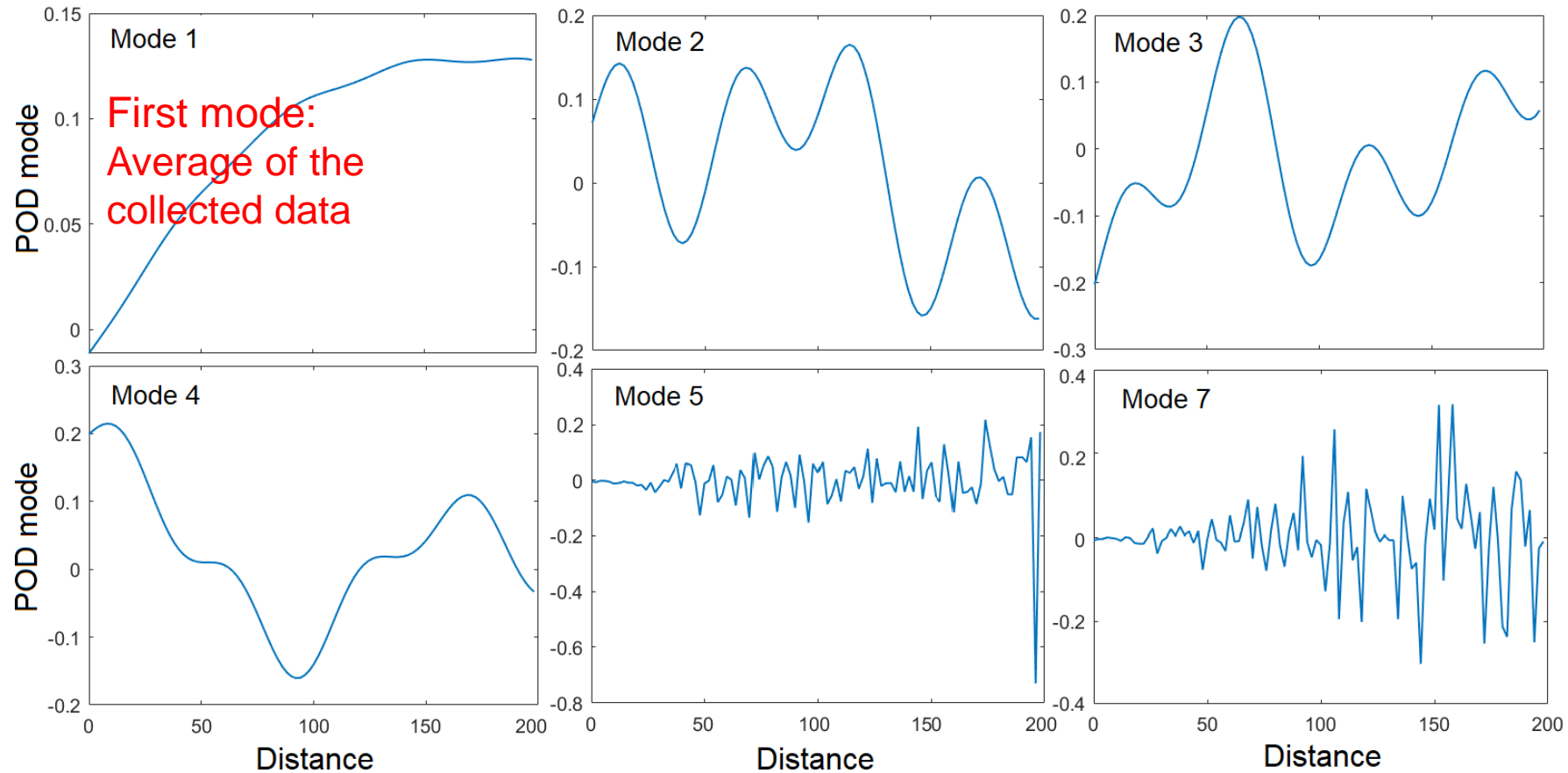


Eigenvalue Number



POD Modes

Normalize the POD mode; i.e., make $\sum_{k=1}^{N_x} |\eta_j(x_k)|^2 = 1$ for $j = 1$ to N_x



Orthonormality

Verify the orthonormality

$$\text{i.e., } \sum_{k=1}^{N_x} \eta_i(x_k) \eta_j(x_k) = \delta_{ij}$$

```
% Verify the orthonormality
modeij_sum = zeros(10,10);
for i = 1:10
    for j = 1:10
        modeij_sum(i,j) = sum(V1(:,i).*V1(:,j));
    end
end
```

modeij_sum x

10x10 double

	1	2	3	4	5	6	7	8	9	10
1	1.0000	-6.9389e-17	-1.8215e-17	-1.0408e-16	1.3184e-16	1.2490e-16	1.0192e-17	9.5410e-18	-2.7756e-17	9.2157e-18
2	-6.9389e-17	1.0000	-2.4286e-17	-1.3791e-16	1.1796e-16	-1.9429e-16	-1.1948e-16	-5.2042e-18	1.2750e-16	-2.4937e-17
3	-1.8215e-17	-2.4286e-17	1.0000	-1.3791e-16	6.2450e-17	-1.3878e-17	1.7022e-17	3.1659e-17	5.6379e-18	-1.8513e-17
4	-1.0408e-16	-1.3791e-16	-1.3791e-16	1.0000	9.5410e-18	0	1.0029e-17	1.1926e-17	8.3917e-17	1.1506e-17
5	1.3184e-16	1.1796e-16	6.2450e-17	9.5410e-18	1.0000	2.2204e-16	8.2616e-17	8.7604e-17	-2.8623e-17	7.3726e-18
6	1.2490e-16	-1.9429e-16	-1.3878e-17	0	2.2204e-16	1	-2.9490e-17	-1.1102e-16	-4.8572e-17	-2.1142e-17
7	1.0192e-17	-1.1948e-16	1.7022e-17	1.0029e-17	8.2616e-17	-2.9490e-17	1.0000	-1.5938e-17	-1.8377e-17	-4.8654e-18
8	9.5410e-18	-5.2042e-18	3.1659e-17	1.1926e-17	8.7604e-17	-1.1102e-16	-1.5938e-17	1.0000	-3.0011e-16	1.0503e-17
9	-2.7756e-17	1.2750e-16	5.6379e-18	8.3917e-17	-2.8623e-17	-4.8572e-17	-1.8377e-17	-3.0011e-16	1.0000	-6.1925e-17
10	9.2157e-18	-2.4937e-17	-1.8513e-17	1.1506e-17	7.3726e-18	-2.1142e-17	-4.8654e-18	1.0503e-17	-6.1925e-17	1.0000



Method of Snapshots: $A_{ij} = \frac{1}{N_s} \int_{\Omega} Q(\vec{r}, t_i) Q(\vec{r}, t_j) d\Omega$

$$F_{snap} = \frac{1}{N_s} \sum_{i=1}^{N_x} \begin{bmatrix} f(x_i, t_1) \\ f(x_i, t_2) \\ \vdots \\ f(x_i, t_{N_s}) \end{bmatrix} \cdot \begin{bmatrix} f(x_i, t_1) \\ f(x_i, t_2) \\ \vdots \\ f(x_i, t_{N_s}) \end{bmatrix}^T$$

% Average of the snapshot matrix over space

```
F_snap = zeros(Ns,Ns);
```

```
for i = 1:Nx
```

```
    F_snap = F_snap + ff_t(i,:)'*ff_t(i,:);
```

```
end
```

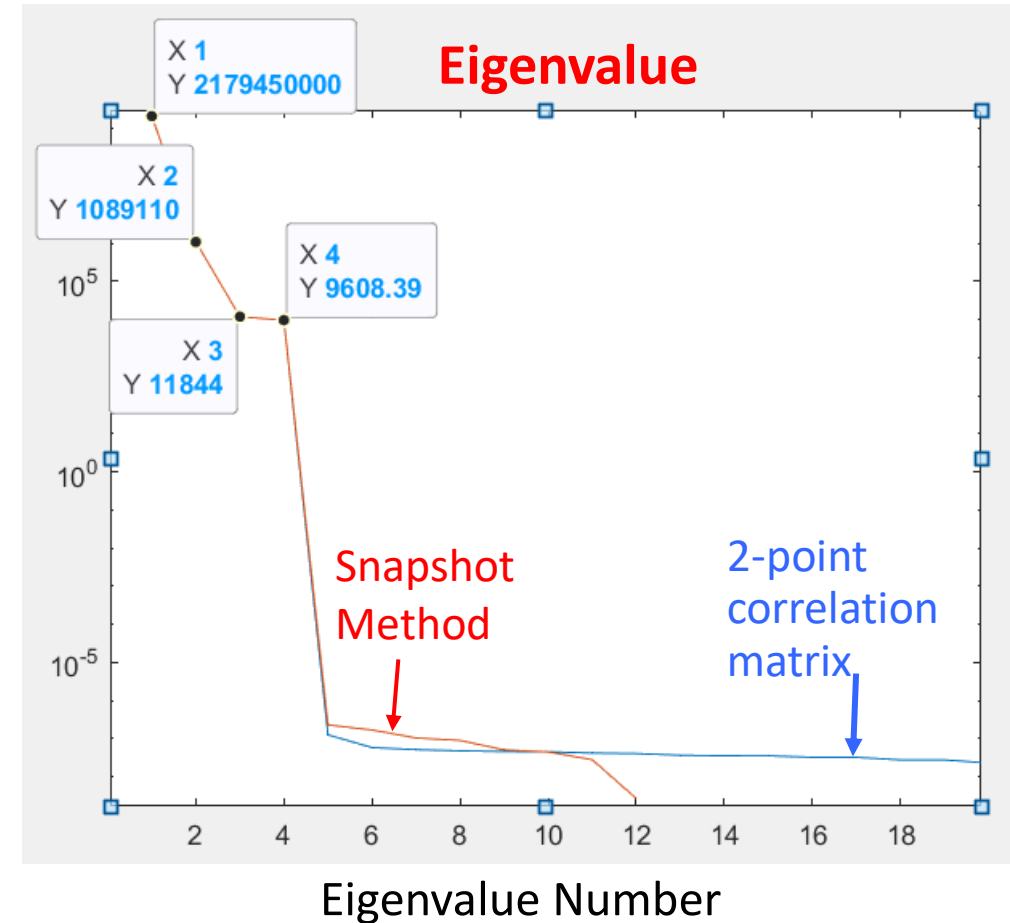
```
F_snap = F_snap/Ns;
```

```
[Vsnap,Dsnap] = eig(F_snap);
```

```
EigenVsnap = flip(diag(Dsnap));
```

```
V1snap = flip(Vsnap,2);
```

```
semilogy(EigenVsnap);
```



The eigenvalues generated from the method of snapshots are identical to the first N_s eigenvalues calculated from the autocorrelation (2-point correlation) matrix.



Next. obtain POD Modes from

- 2-point correlation (autocorrelation) matrix
- Method of Snapshots

Verify that they are indeed identical for the first 4 modes.

Plot modes from these 2 approaches on top of each other for the first 6 modes

POD modes derived from the 2-point correlation matrix

